

EasyDriver v4.2

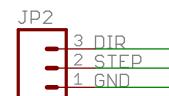
An easy to use bipolar stepper motor driver
Use 4 wire, 6 wire or 8 wire steper motors
From about 150mA/phase to about 750mA/phase
Defaults to 5V for Vcc (logic supply), settable to 3.3V
Supply 8V to 30V DC power input on JP1
Do not connect or disconnect motor
while EasyDriver is powered

DEFAULT OPTIONS
Short JP5, JP6, JP7 pins to GND or Vcc to override

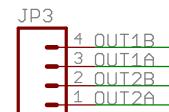
SLEEP = Vcc (awake)
MS1 = Vcc (1/8 microstep)
MS2 = Vcc (1/8 microstep)
ENABLE = GND (enabled)
RESET = Vcc (not reset)
PFD = Vcc (slow decay mode)



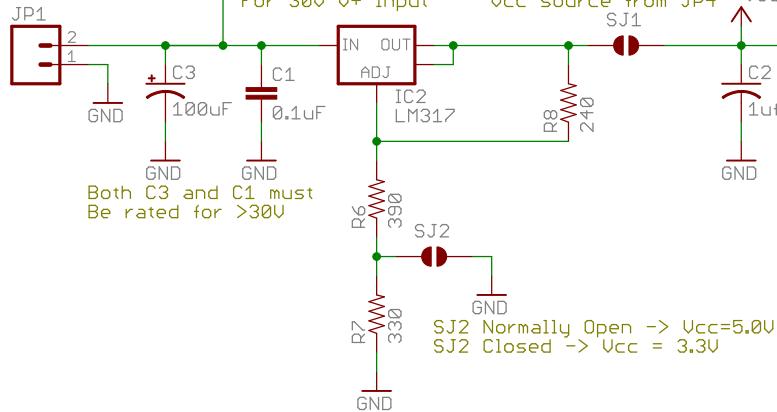
DIR is level sensitive
A rising edge on STEP causes a step
Both take 0V to Vcc



Coil 1 of motor across OUT1B and OUT1A
Coil 2 of motor across OUT2B and OUT2A

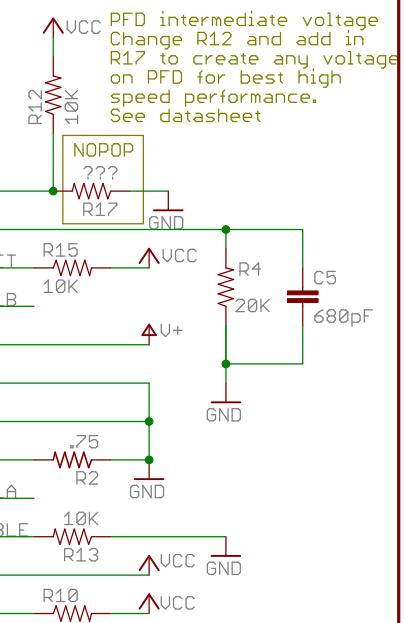
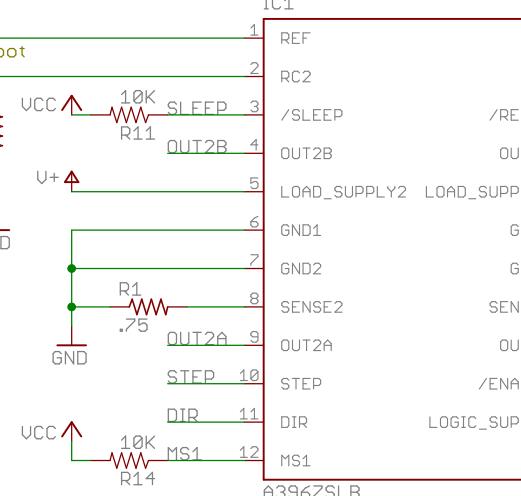


Power Input
8V to 30V (Vcc = 5V)
6.3V to 30V (Vcc = 3.3V)



www.schmalzhaus.com/EasyDriver

TP1 - VREF input to driver
Monitor this test point with meter
as you adjust current adj pot
Valid range 1.0V to Vcc
At VREF of 5V max current will be 833mA
At VREF of 3.3V max current will be 550mA
At VREF of 1V max current will be 166mA
Minimum current gives smoothest microsteps
Maximum current gives highest torque



EasyDriver v4.2 by Brian Schmalz is licensed under a Creative Commons Attribution 3.0 US License

Designed by Brian Schmalz

Produce by Spark Fun Electronics

TITLE: EasyDriver_v42-assembly

SFE

Document Number:

REV:

Date: 8/17/2009 5:46:59 PM

Sheet: 1/1